## IMPLEMENTING RIAK IN ERLANG: BENEFITS AND CHALLENGES

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Large number of concurrent activities



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- Large software systems distributed across multiple computers



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## Today's Data/Web/Cloud/ Service Apps

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Tolerance for both hardware and software faults

## CONCURRENCY



# They Come For The Concurrency...

- Erlang processes are very lightweight, much lighter than OS threads
- Hundreds of thousands or even millions of processes per Erlang VM instance





Isolation: Erlang processes communicate only via message passing



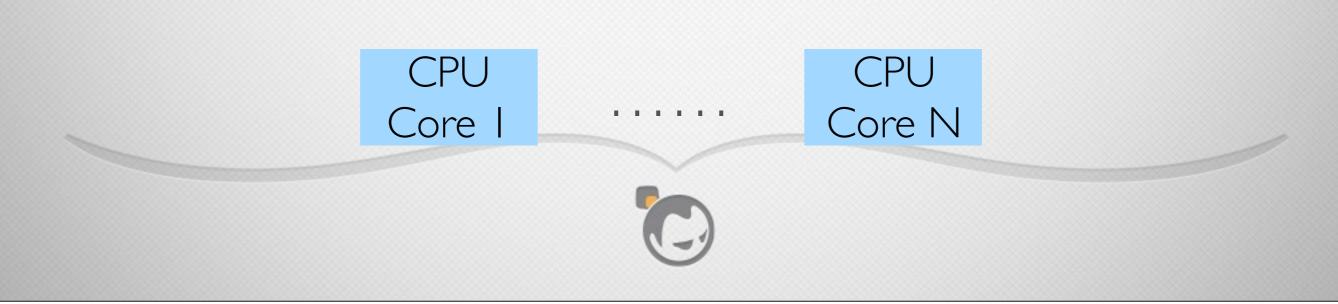
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- Distribution: Erlang process model works across nodes

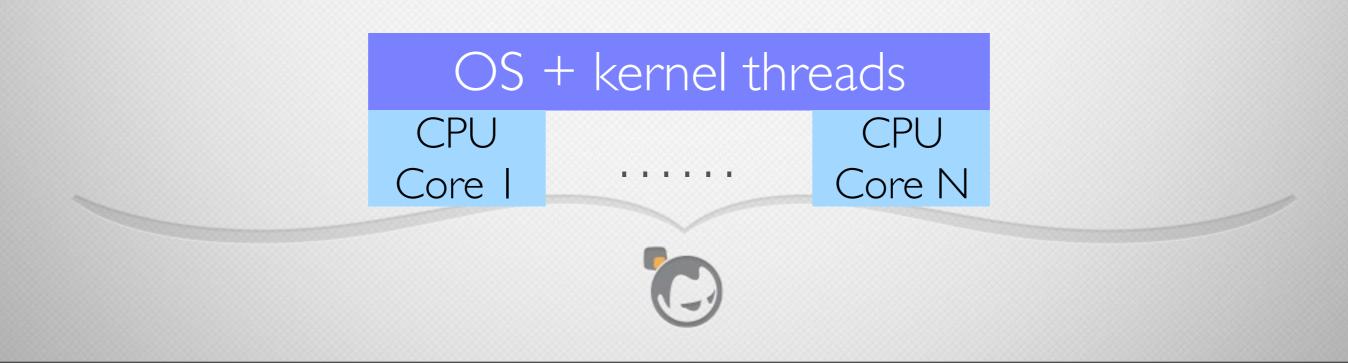


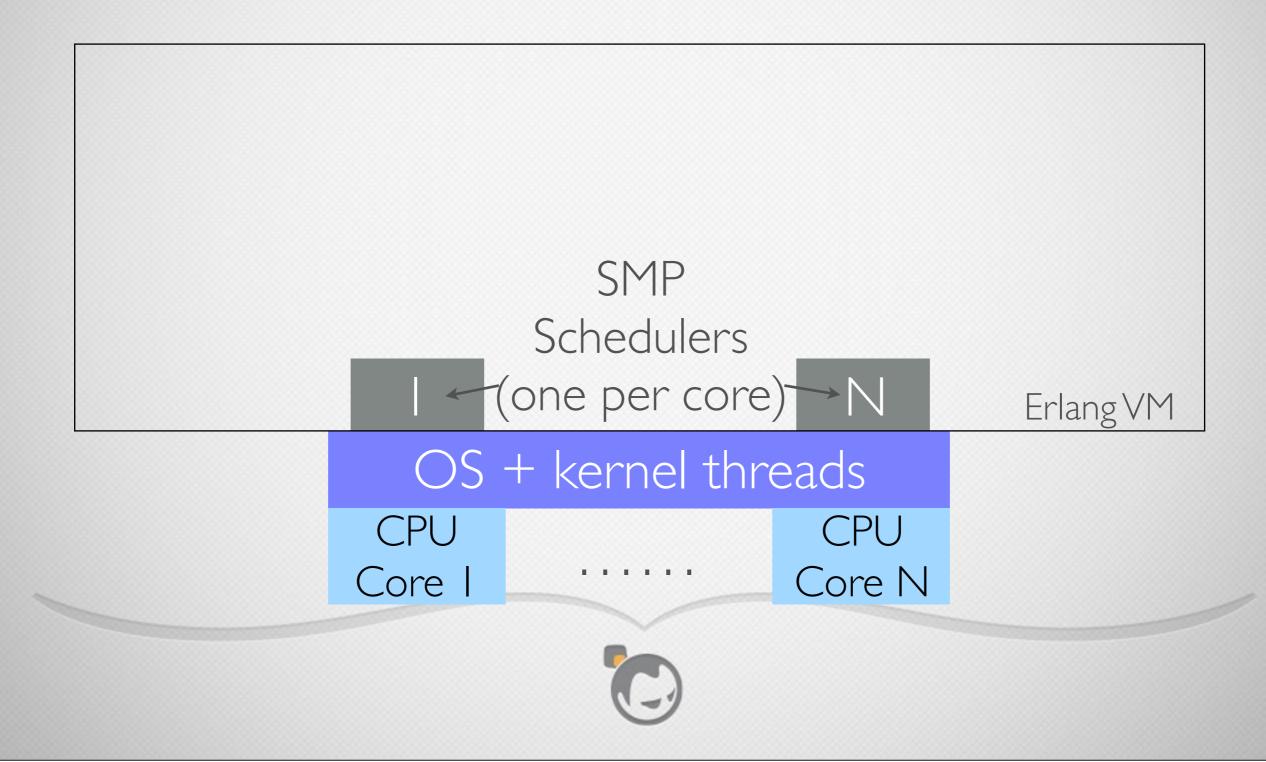
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- Distribution: Erlang process model works across nodes
- Linking/supervision/monitoring: allow an Erlang process to take action when another fails

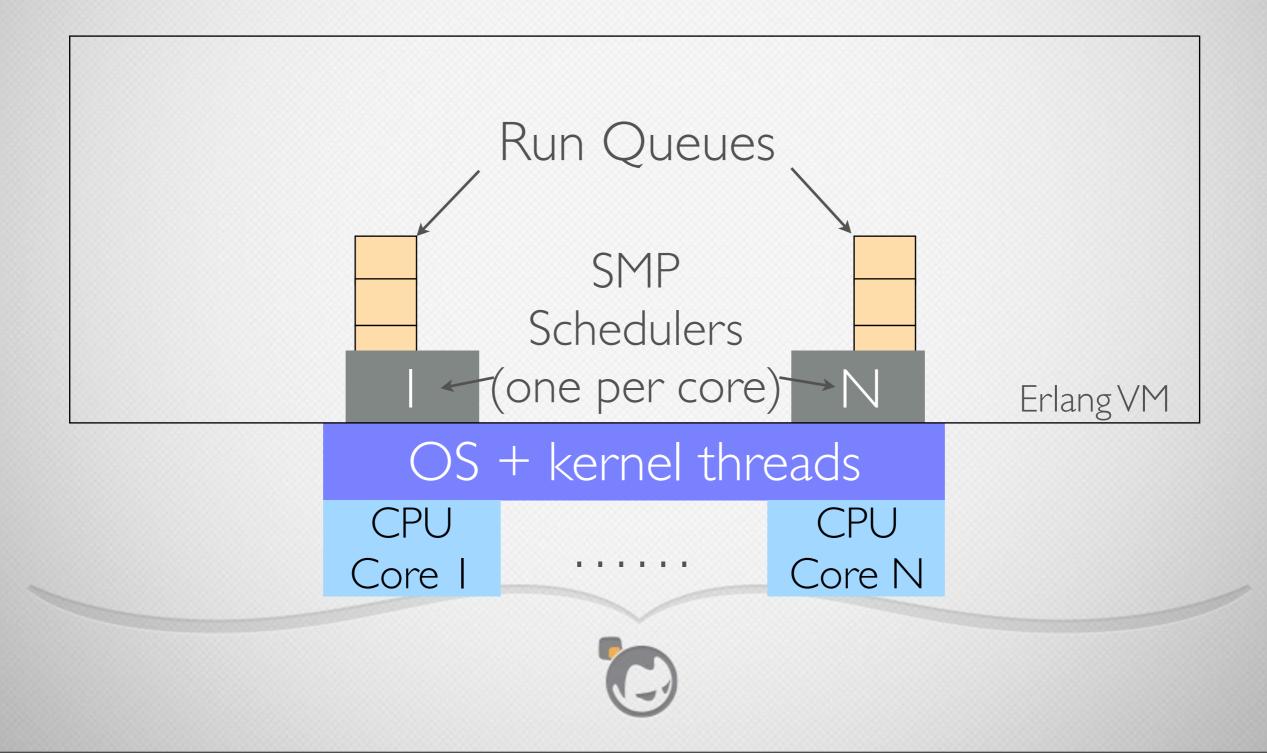


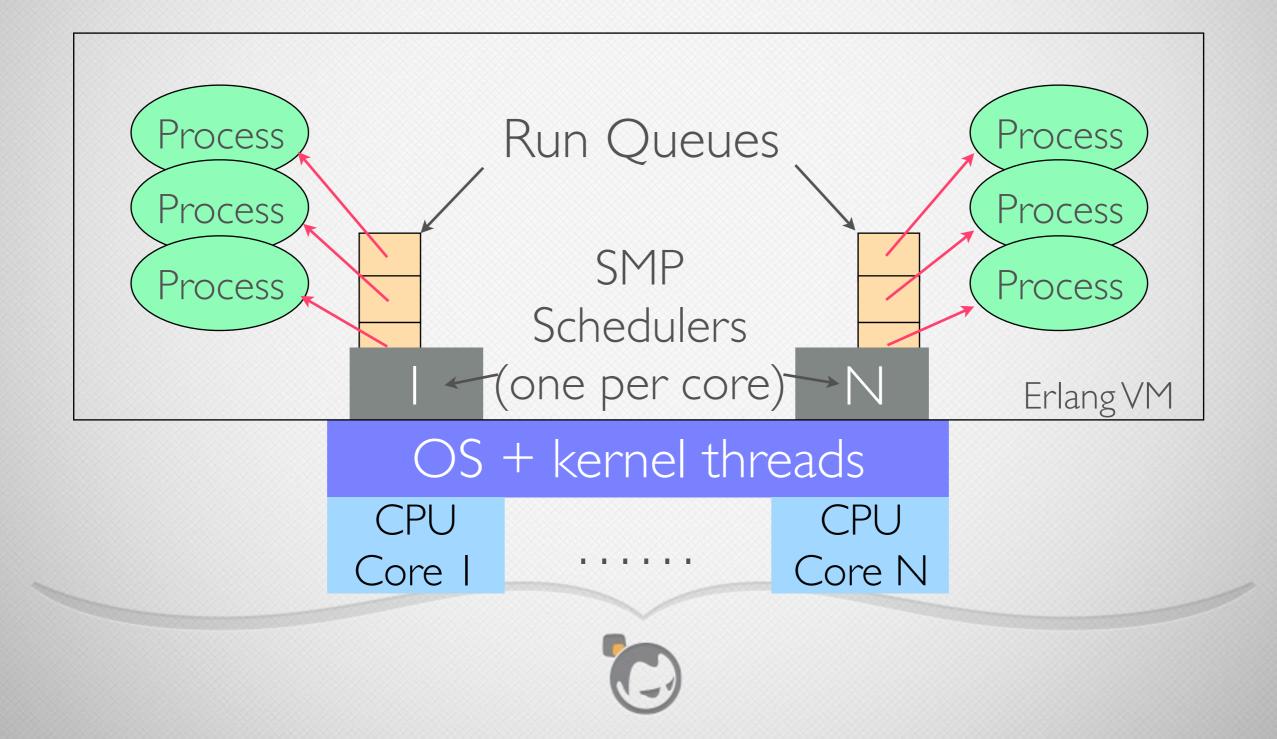














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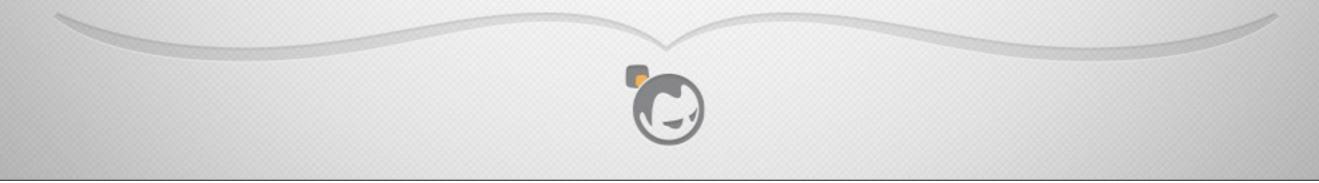


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- Variables are immutable, no globals
- Flow control via pattern matching, case, if, try-catch, recursion, messages



## **Concurrency Primitives**

- No mutexes, condition variables, or other error-prone concurrency constructs
- All Erlang code runs within some process, always
  - processes are not "extra" like threads in other languages



## **Concurrency Primitives**

- spawn: create a new Erlang process
- ! (exclamation point) or send: send a message to another Erlang process, even on another node
- Messages can be any Erlang term
- Messages from A to B arrive in the order sent

Pid1 ! ok, Pid2 ! [{first, "John"},{last,"Doe"}].



## **Concurrency Primitives**

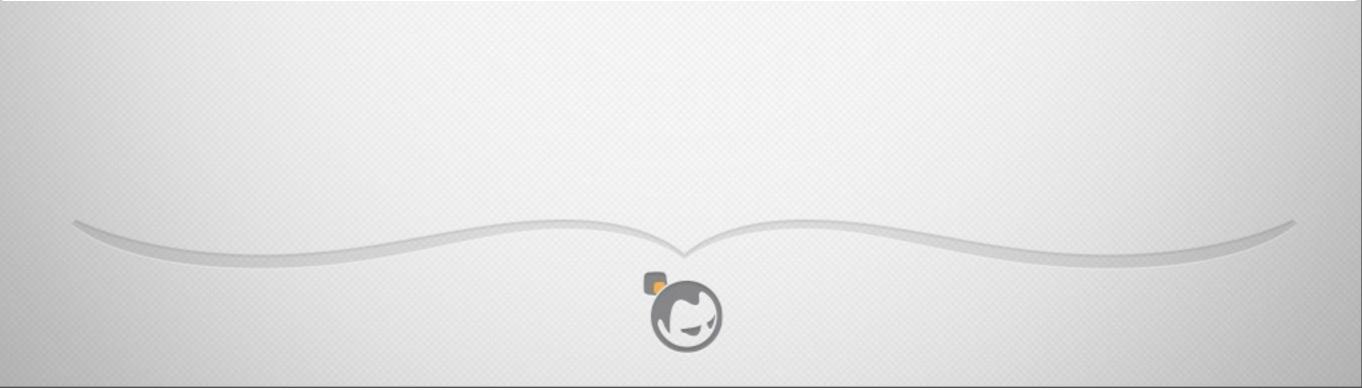
- Each process has a message queue
- receive: receive a message from another Erlang process
- Selective receive allows receiving specific messages from anywhere within the message queue

```
receive
{ok, Reply} ->
do_something(Reply);
{error, Error} ->
uh_oh(Error)
end.
```

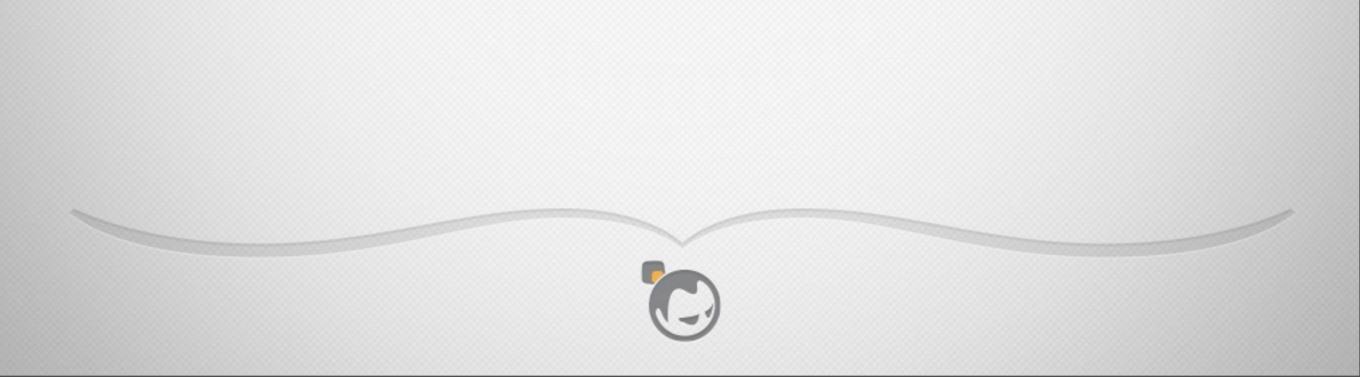
- Erlang assignment is pattern matching, not mutation
- Unbound variables get the value of the right-hand side and then can't be changed



## foo() -> A = 2, % A is bound to 2

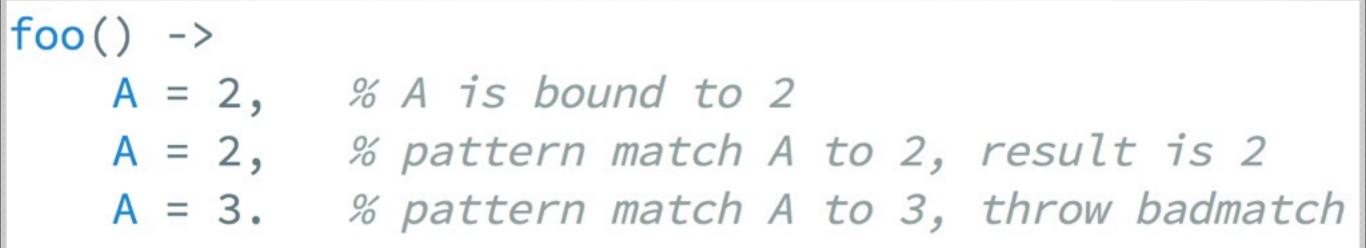


# foo() -> A = 2, % A is bound to 2 A = 2, % pattern match A to 2, result is 2











## Easy To Learn

- Language size means developers become proficient quickly
- Code is typically brief, easy to read, easy to understand
- Erlang's Open Telecom Platform (OTP) frameworks solve recurring problems across multiple domains



## Riak



• A distributed



#### • A distributed highly available



#### • A distributed highly available eventually consistent



• A distributed highly available eventually consistent highly scalable



• A distributed highly available eventually consistent highly scalable open source



• A distributed highly available eventually consistent highly scalable open source key-value database



 A distributed highly available eventually consistent highly scalable open source key-value database written primarily in Erlang.



- Modeled after Amazon Dynamo
  - see Andy Gross's "Dynamo, Five Years Later" for details https://speakerdeck.com/argv0/dynamo-five-years-later
- Also provides MapReduce, secondary indexes, and fulltext search
- Built for operational ease

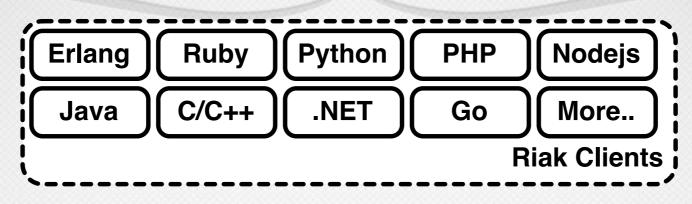


image courtesy of Eric Redmond, "A Little Riak Book" <u>https://github.com/coderoshi/little\_riak\_book/</u>

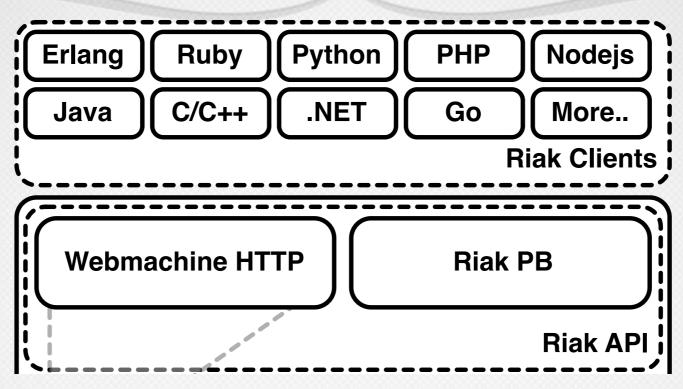


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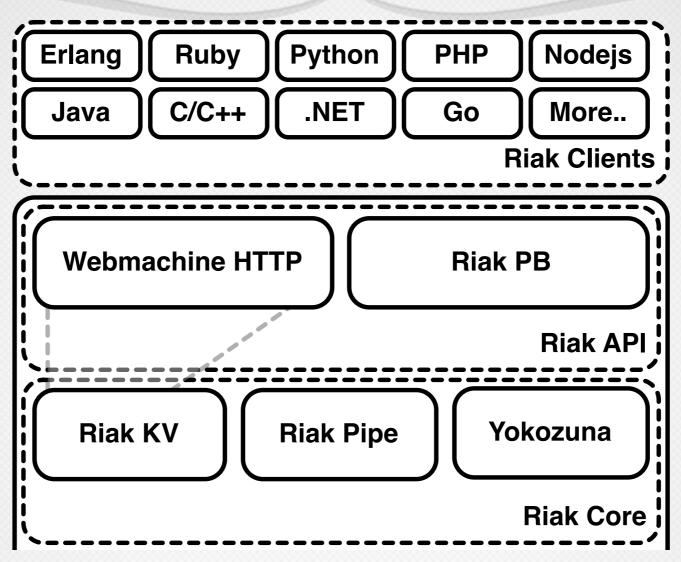
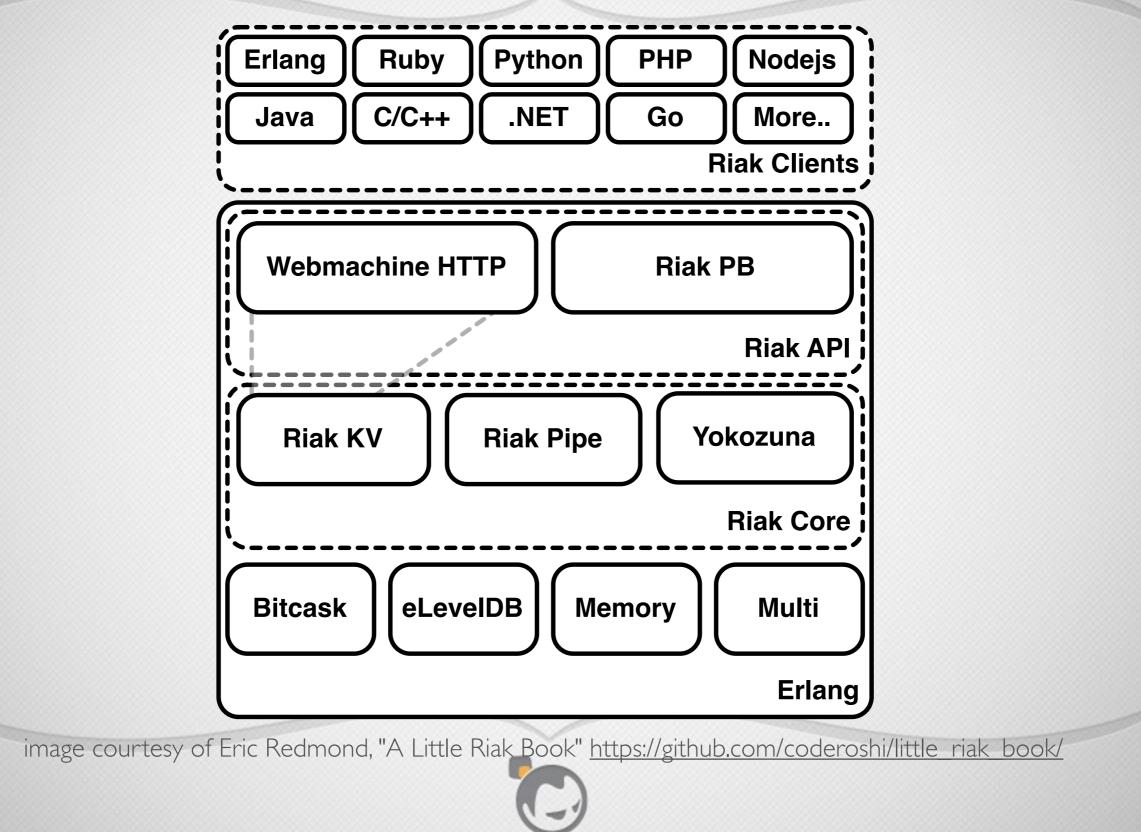
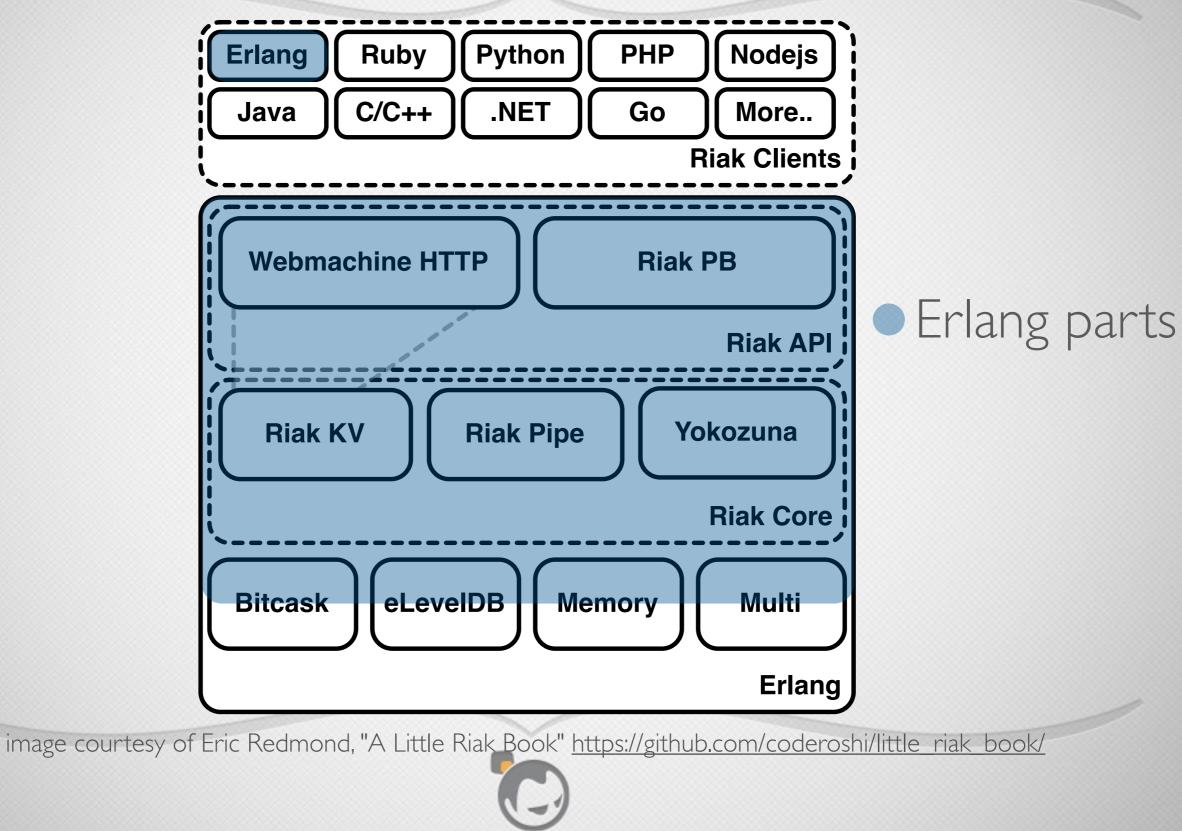
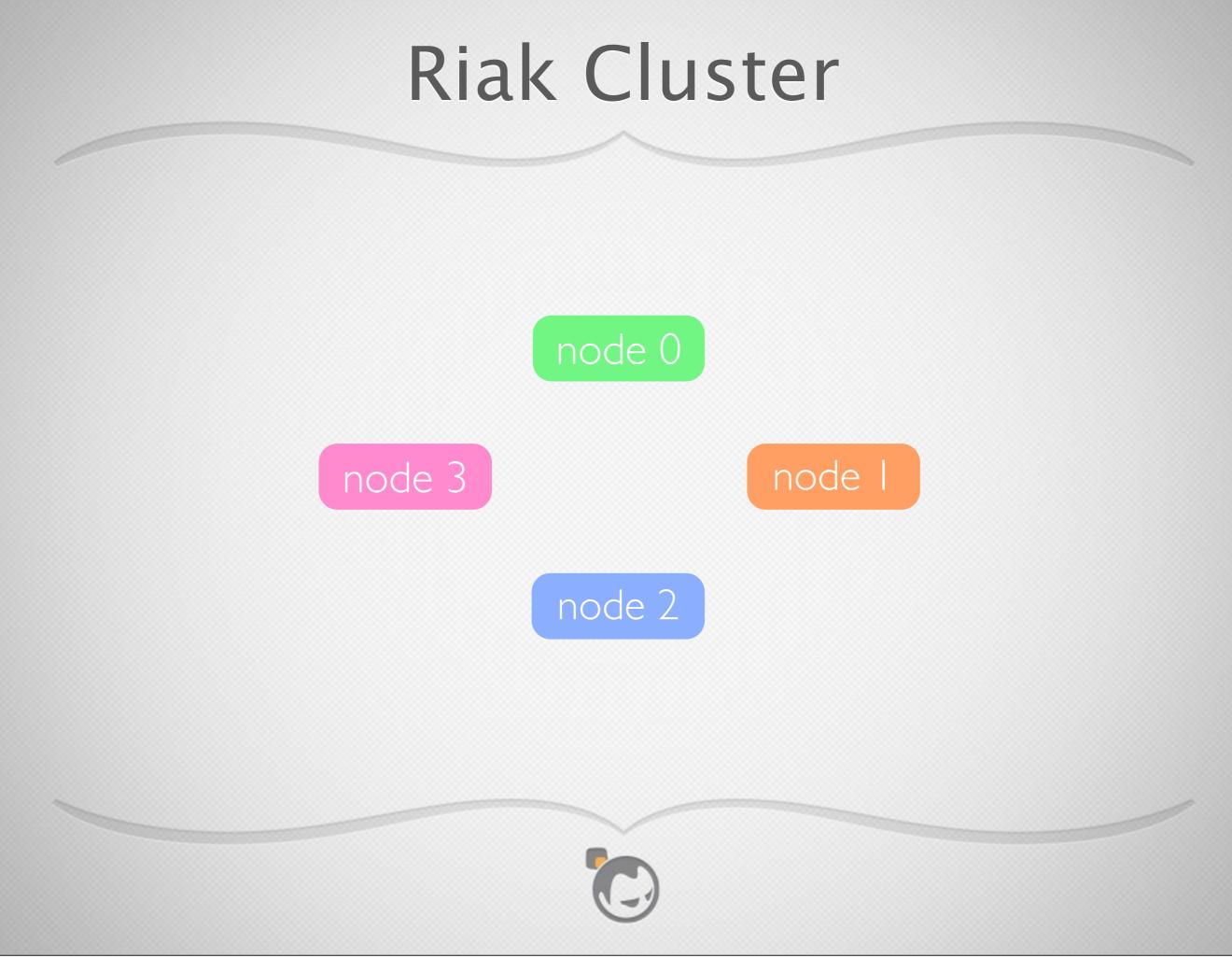


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# **Distributing Data**

- Riak uses consistent hashing to spread data across the cluster
- Minimizes remapping of keys when number of nodes changes
- Spreads data evenly and minimizes hotspots

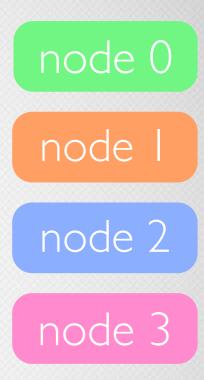
node 0
node I
node 2
node 3





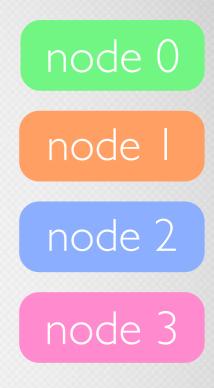


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- Treats its 160-bit value space as a ring
- Divides the ring into partitions called "virtual nodes" or vnodes (default 64)
- Each vnode claims a portion of the ring space
- Each physical node in the cluster hosts multiple vnodes

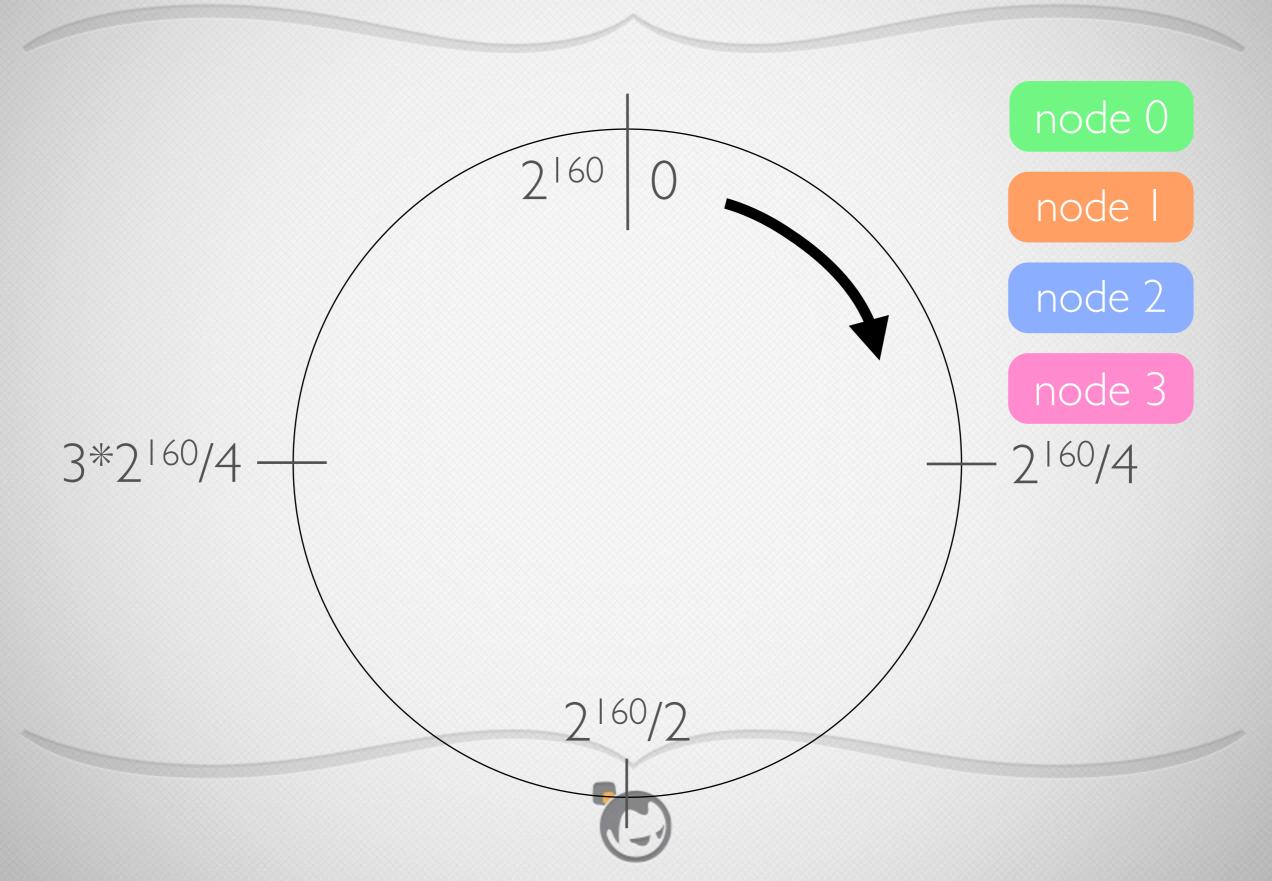
node 0

node l

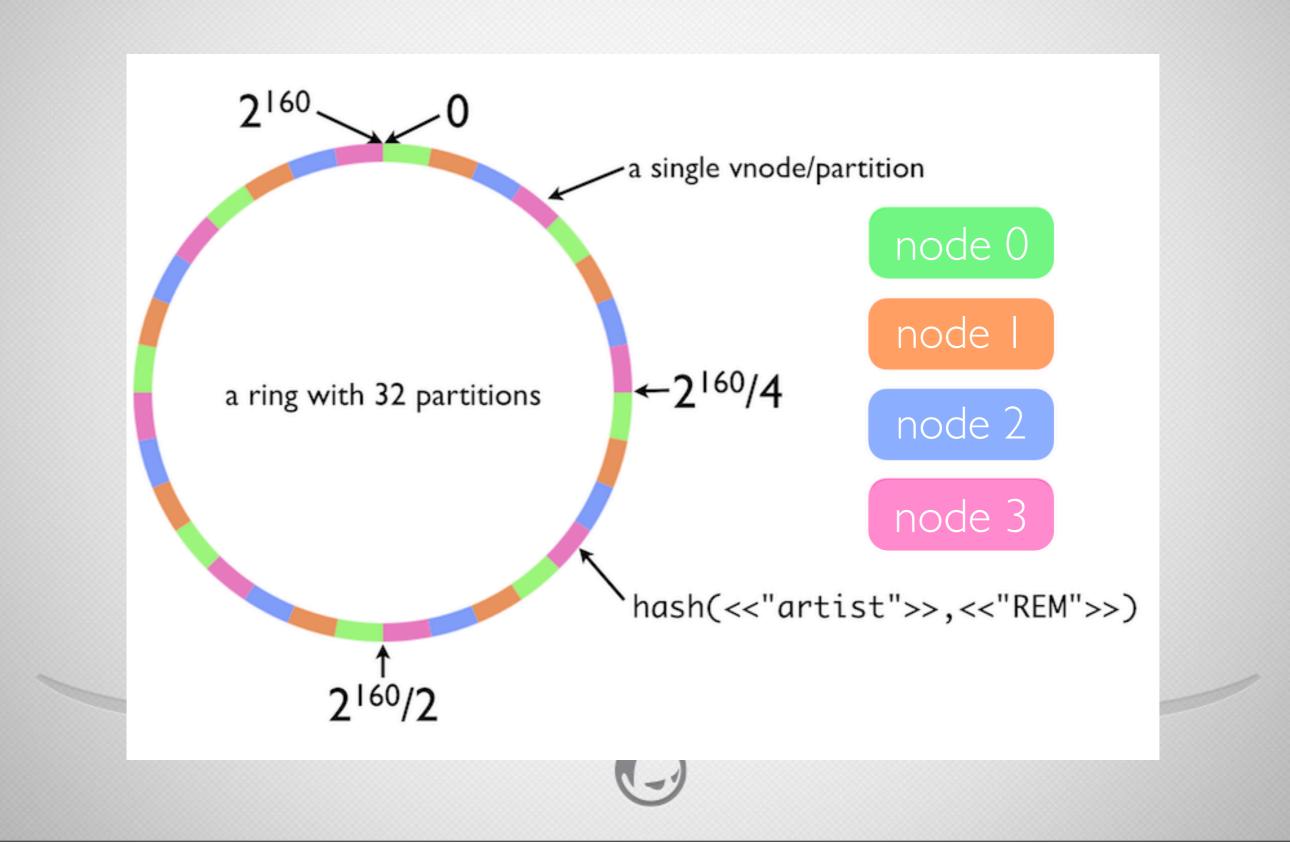
node 2

node 3

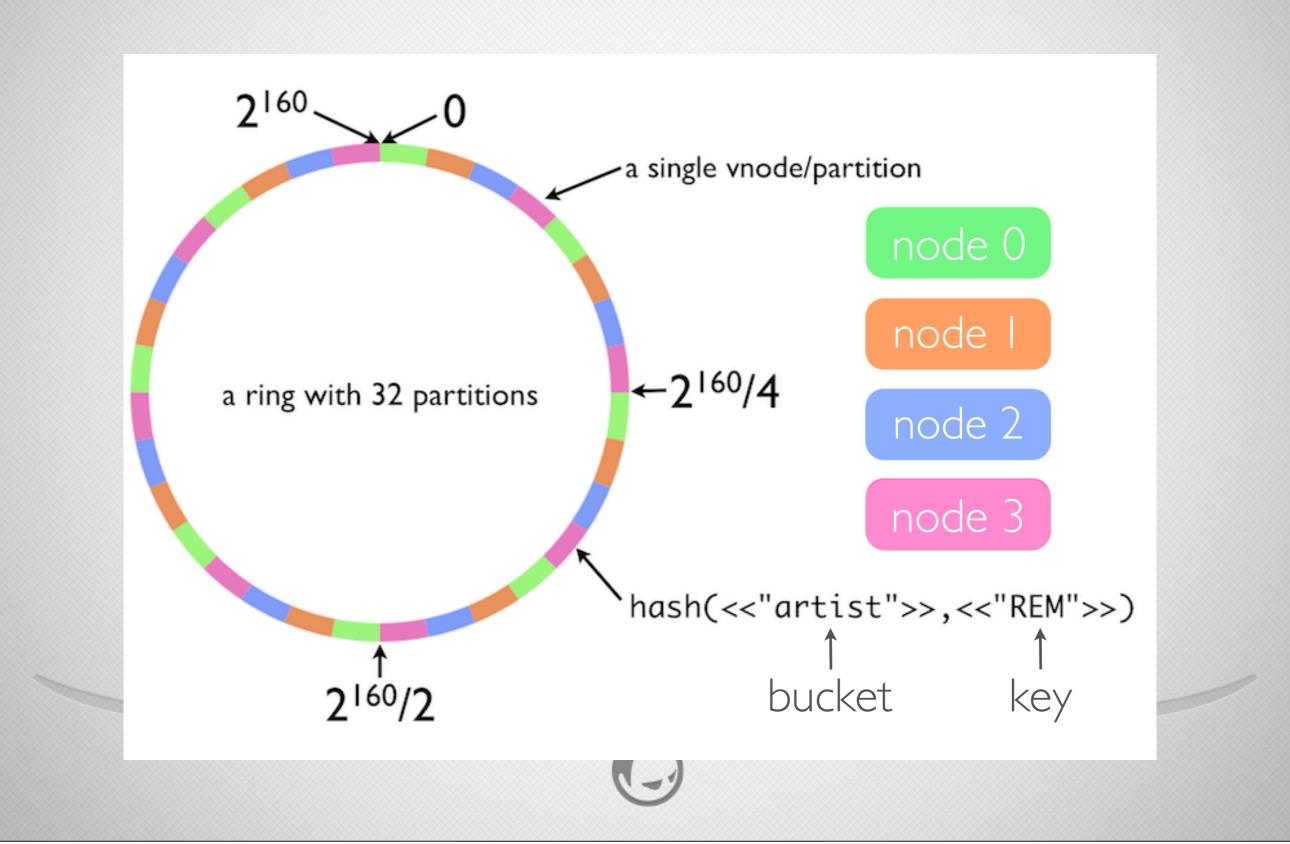
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 N = number of replicas to store (default 3, can be set per bucket)

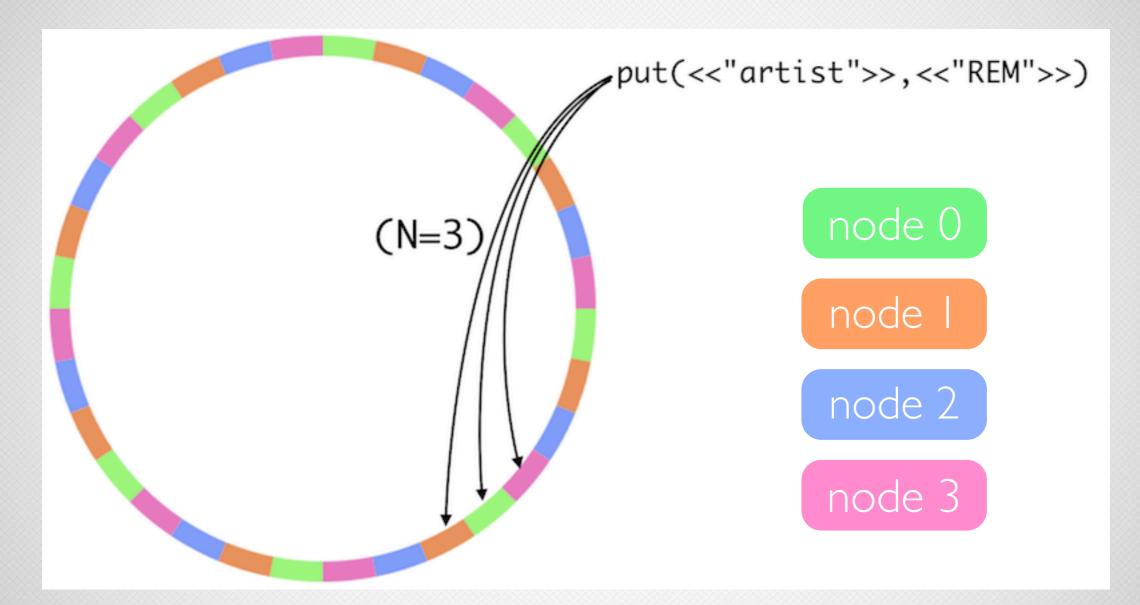


- N = number of replicas to store (default 3, can be set per bucket)
- R = read quorum = number of replica responses needed for a successful read (can be specified per-request)



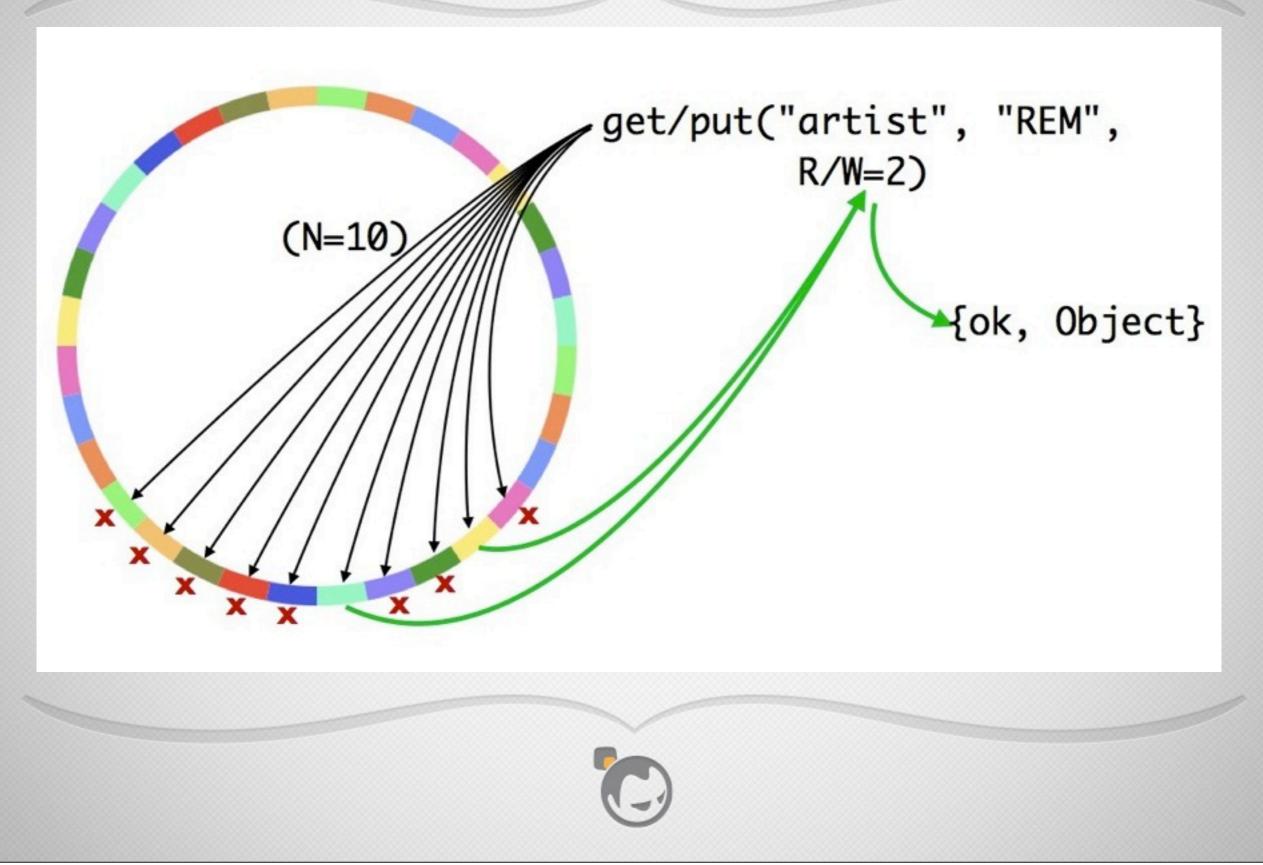
- N = number of replicas to store (default 3, can be set per bucket)
- R = read quorum = number of replica responses needed for a successful read (can be specified per-request)
- W = write quorum = number of replica responses needed for a successful write (can be specified perrequest)

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for details see <a href="http://docs.basho.com/riak/1.3.1/tutorials/fast-track/Tunable-CAP-Controls-in-Riak/">http://docs.basho.com/riak/1.3.1/tutorials/fast-track/Tunable-CAP-Controls-in-Riak/</a>







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- Erlang's crypto module integration with OpenSSL provides the SHA-1 function
- Hash values are 160 bits
- But that's OK, Erlang's integers are infinite precision
- And Erlang binaries store these large values efficiently

1> HashBin = crypto:sha("my object key").



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3> <<HashInt:160/integer>> = HashBin.
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1080638148638140855100958270058021626367330918047
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5> rp(riak_core_ring_manager:get_my_ring()).
{ok, {chstate_v2, 'dev1@127.0.0.1',
                [{'dev1@127.0.0.1', {211, 63521635595}},
                 {'dev2@127.0.0.1', {3,63521635521}},
                 {'dev3@127.0.0.1', {3,63521635544}}],
                {64,
                 [{0, 'dev1@127.0.0.1'},
                   {22835963083295358096932575511191922182
123945984,
                    'dev2@127.0.0.1'},
                   {45671926166590716193865151022383844364
247891968,
```

## **Ring State**

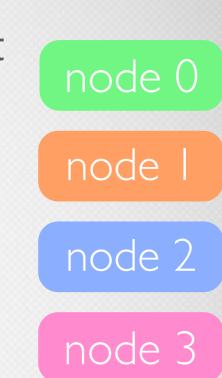
- All nodes in a Riak cluster are peers, no masters or slaves
- Nodes exchange their understanding of ring state via a gossip protocol



- Erlang has distribution built in it's required for supporting multiple nodes for reliability
- By default Erlang nodes form a mesh, every node knows about every other node
- Riak uses this for intra-cluster communication



- Riak lets you simulate a multi-node installment on a single machine, nice for development
- "make devrel" or "make stagedevrel" in a riak repository clone (git://github.com/basho/riak.git)
- Let's assume we have nodes dev1, dev2, and dev3 running in a cluster, nothing on the 4th node yet
- Instead of starting riak, let's start the 4th node as just a plain distributed erlang node



\$ erl -name dev4@127.0.0.1 -setcookie riak
Erlang R15B01 (erts-5.9.1) [source] [64-bit] [smp:8:8]
[async-threads:0] [kernel-poll:false]

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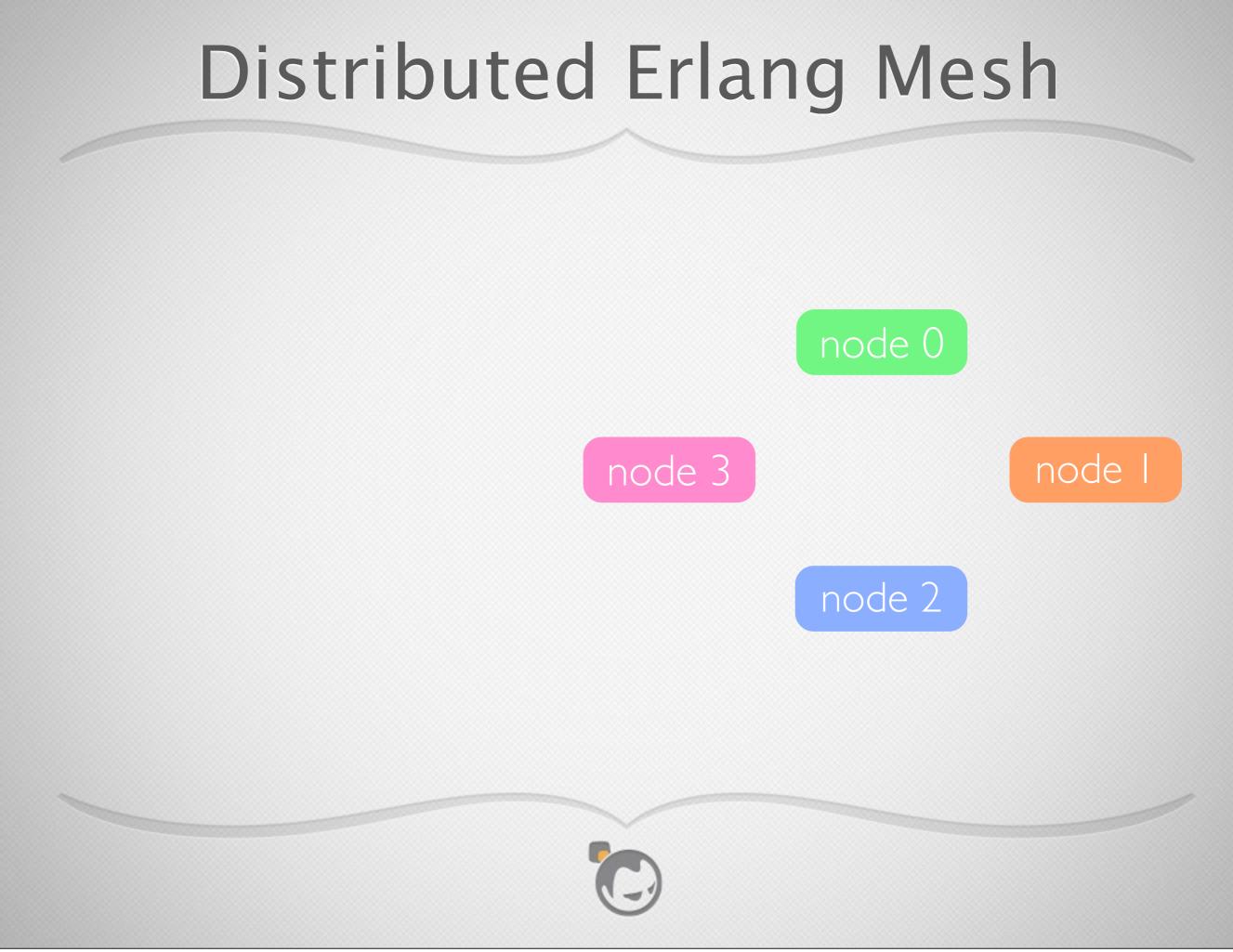
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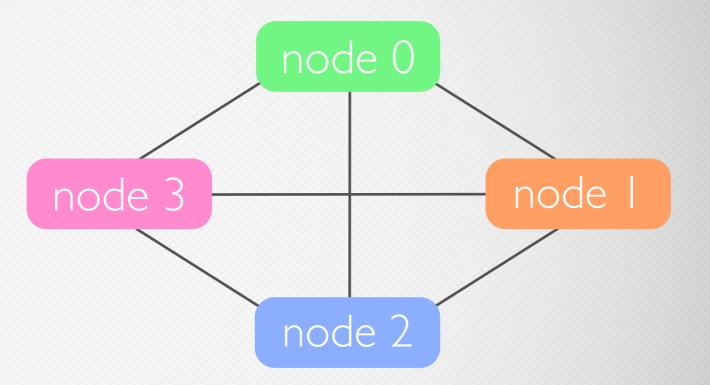
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(dev4@127.0.0.1)3> nodes().
['dev1@127.0.0.1','dev3@127.0.0.1','dev2@127.0.0.1']

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Erlang R15B01 (erts-5.9.1) [source] [64-bit] [smp:8:8]
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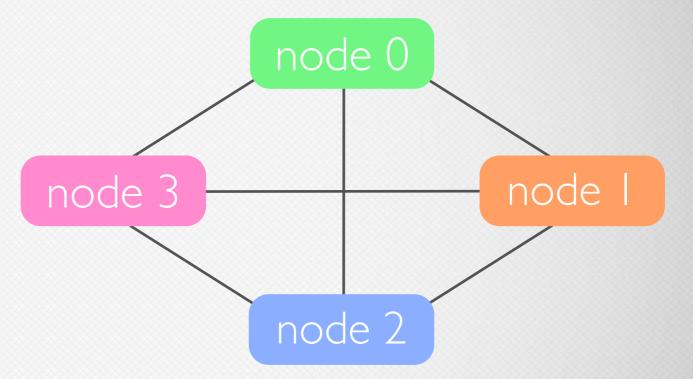
```
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[]
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pong
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```





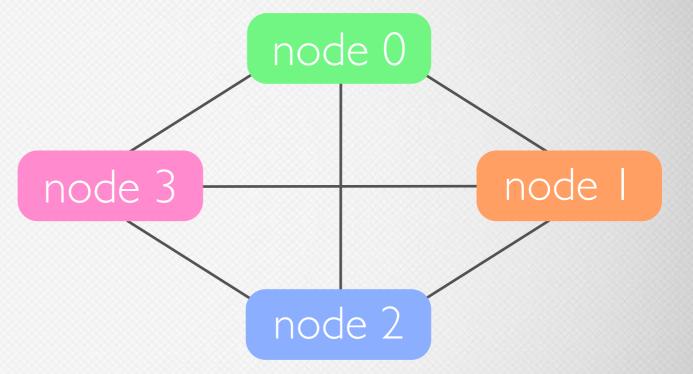


 Nodes talk to each other occasionally to check liveness



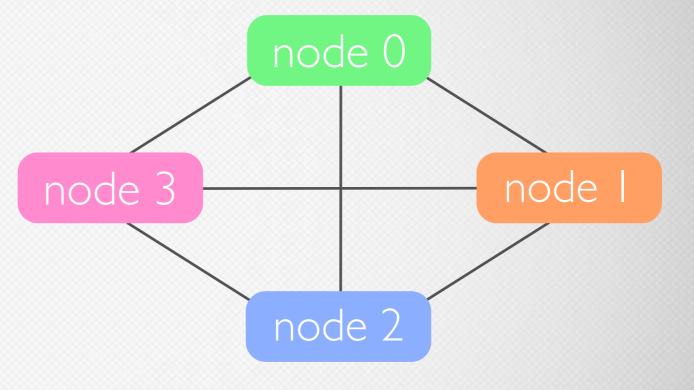


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- Nodes talk to each other occasionally to check liveness
- Mesh approach makes it easy to set up a cluster
- But communication overhead means it doesn't scale to large clusters > 150 nodes (yet)



## Gossip

- Riak nodes are peers, there's no master
- But the ring has state, such as what vnodes each node has claimed
- Nodes periodically send their understanding of the ring state to other randomly chosen nodes
- Riak gossip module also provides an API for sending ring state to specific nodes



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- Sending large data can cause busy distribution ports and head-of-line blocking



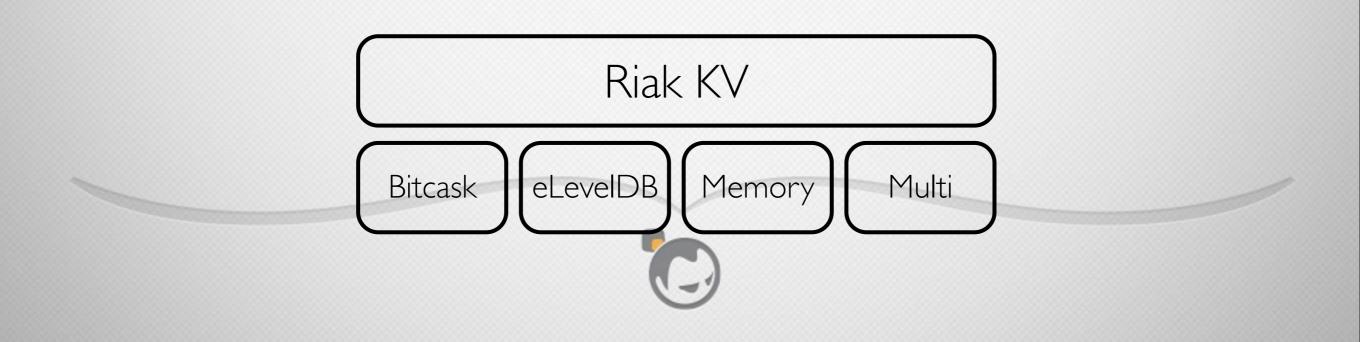
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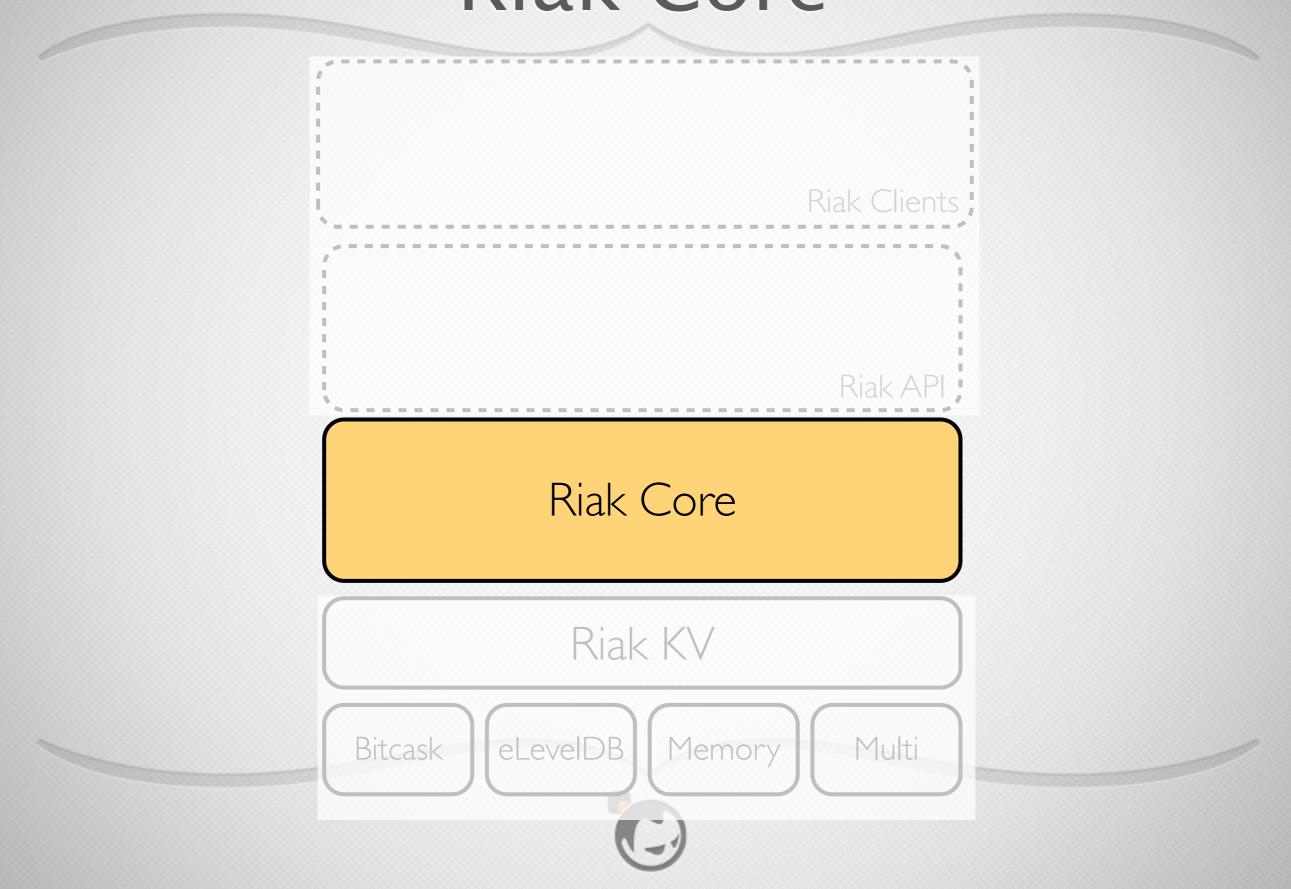
- Distributed Erlang: good for control plane, not so good for data plane
- Sending large data can cause busy distribution ports and head-of-line blocking
- Use TCP, UDP, etc. directly for data plane traffic
- Don't mix control plane and data plane traffic
  - unfortunately Riak currently still does this in a few places

#### Riak Core

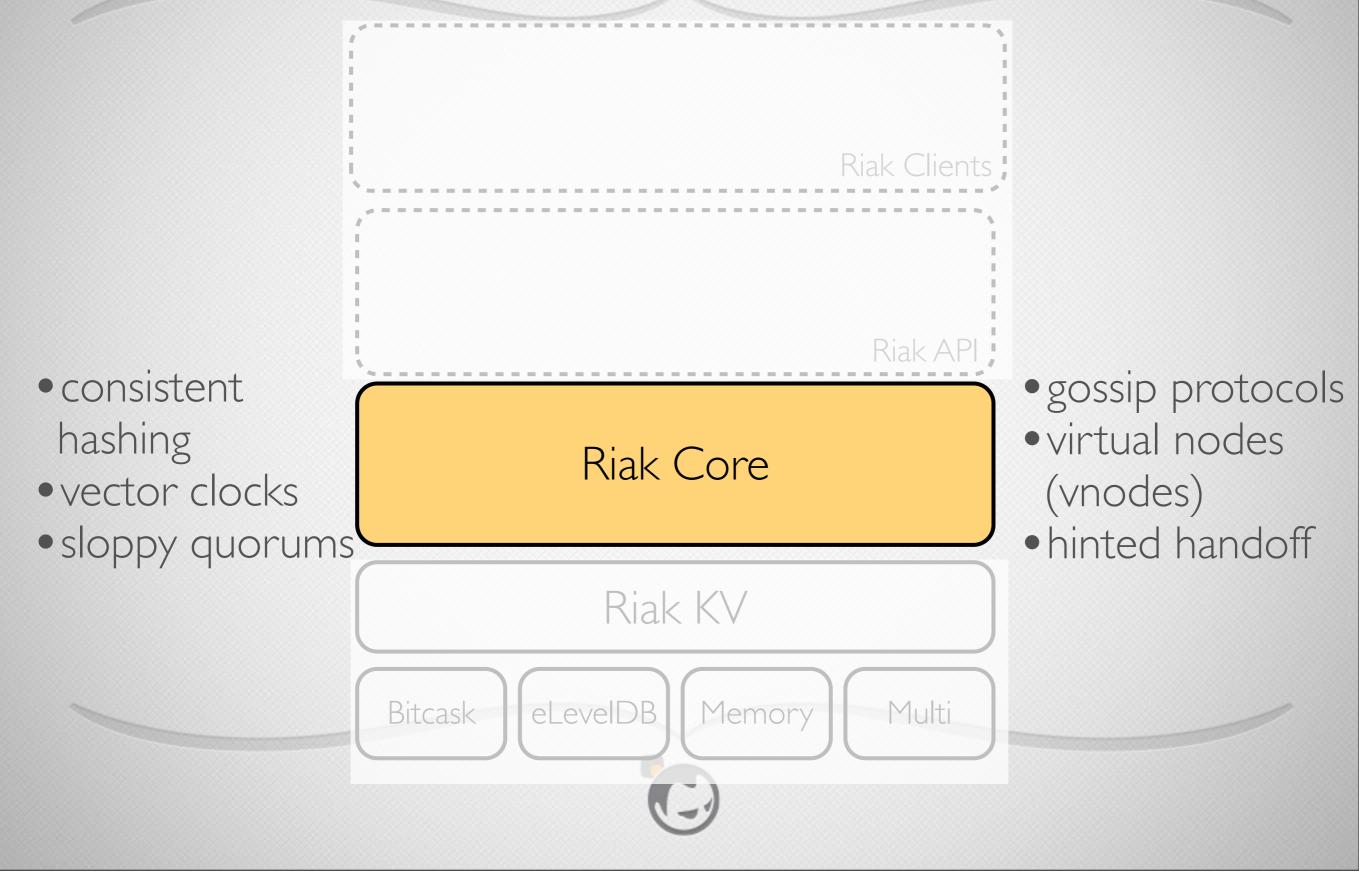




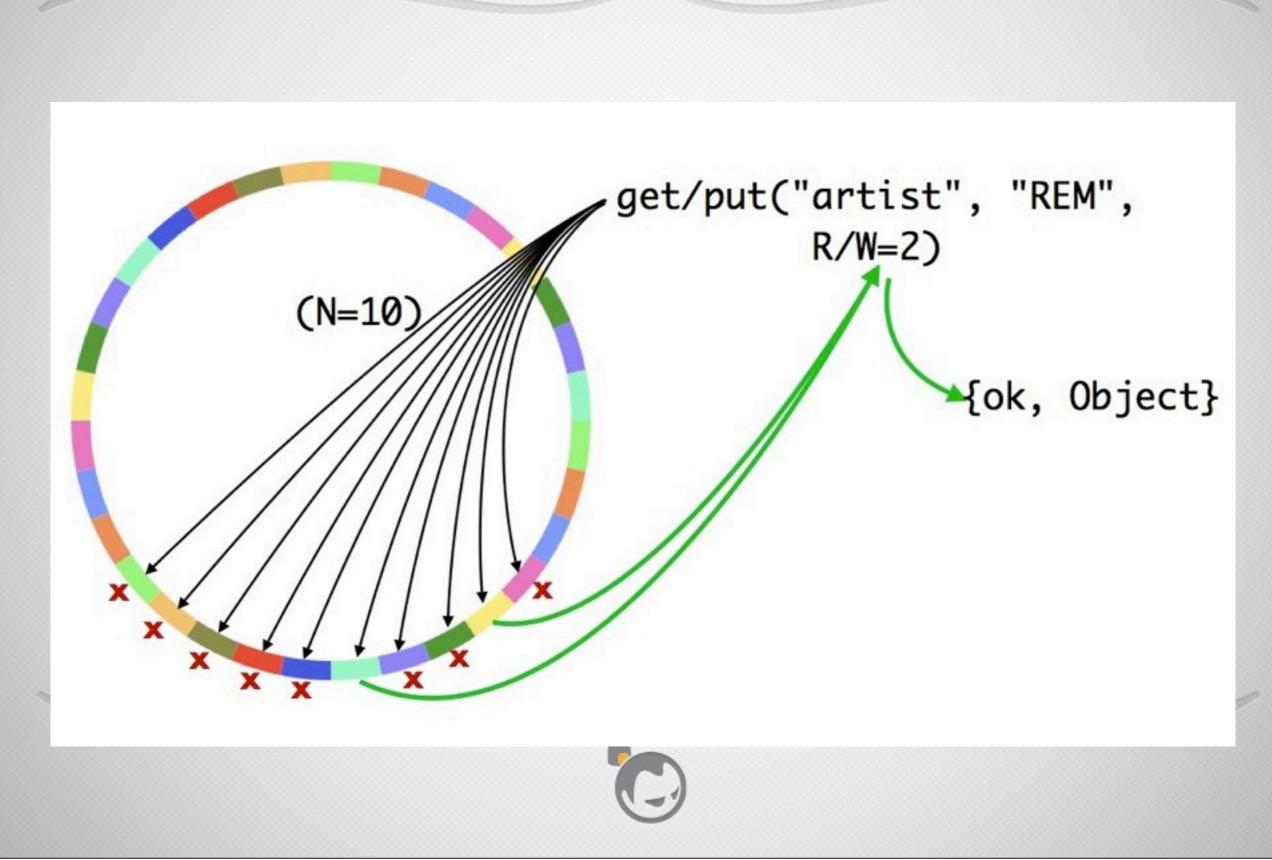
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# N/R/W Values



#### Hinted Handoff



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• Fallback vnode holds data for unavailable primary vnode



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- Fallback vnode holds data for unavailable primary vnode
- Fallback vnode keeps checking for availability of primary vnode
- Once primary vnode becomes available, fallback hands off data to it
- Fallback vnodes are started as needed, thanks to Erlang lightweight processes

#### **Read Repair**

- If a read detects a vnode with stale data, it is repaired via asynchronous update
- Helps implement eventual consistency
- Starting at version 1.3, Riak supports active antientropy (AAE) to actively repair stale values



#### **Core Protocols**

- Gossip, handoff, read repair, etc. all require intracluster protocols
- Erlang distribution and other features help significantly with protocol implementations
- Erlang monitors allow processes and nodes to watch each other while interacting
  - A monitoring process/node is notified if a monitored process/node dies, great for aborting failed interactions

- Erlang's binaries make working with network packets easy
- For example, deconstructing a TCP message (from Cesarini & Thompson "Erlang Programming")

														т	PH	lead	der																
Offsets	Octet	0							1							2								3									
Octet	Bit	0	1 2	3	4	5	6	7	8	9 :	10	11	12	13	14	15	16	1	7 18	19	2	0 2:	22	2	23	24	25	26	27	28	29	30	31
0	0		Source port														1	Destination port															
4	32		Sequence number																														
8	64		Acknowledgment number (if ACK set)																														
12					Re	ser	ver	N	с	E	U	A	P	R	s	F																	
	96	Da	ata of	fset		0 0		S	WC	C	R	С	S	S	Y	I					Window Size												
							°.	5	R	E	G	ĸ	H	T	N	N																	
16	128		Checksum														Urgent pointer (if URG set)																

source: http://en.wikipedia.org/wiki/Transmission\_Control\_Protocol



#### TcpBuf.



TCP header fields

<<SourcePort:16, DestinationPort:16, SequenceNumber:32, AckNumber:32, DataOffset:4, \_Rsrvd:4, Flags:8, WindowSize:16, Checksum:16, UrgentPtr:16, = TcpBuf.



<<SourcePort:16, DestinationPort:16, SequenceNumber:32, AckNumber:32, DataOffset:4, \_Rsrvd:4, Flags:8, WindowSize:16, Checksum:16, UrgentPtr:16, Data/binary>> = TcpBuf.

TCP data payload



<<SourcePort:16, DestinationPort:16, SequenceNumber:32, AckNumber:32, DataOffset:4, \_Rsrvd:4, Flags:8, WindowSize:16, Checksum:16, UrgentPtr:16, Data/binary>> = TcpBuf.



#### **Protocols With OTP**

- OTP provides libraries of standard modules
- And also behaviors: implementations of common patterns for concurrent, distributed, fault-tolerant Erlang apps



#### **OTP Behavior Modules**

- A behavior is similar to an abstract base class in OO terms, providing:
  - a message handling tail-call optimized loop
  - integration with underlying OTP system for code upgrade, tracing, process management, etc.





• application: plugs into Erlang application controller



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- supervisor: manages and monitors worker processes



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- application: plugs into Erlang application controller
- supervisor: manages and monitors worker processes
- gen\_server: server process framework
- gen\_fsm: finite state machine framework
- gen\_event: event handling framework

#### Gen\_server

- Generic server behavior for handling messages
- Supports server-like components, distributed or not
- "Business logic" lives in app-specific callback module
- Maintains state in a tail-call optimized receive loop



# Gen\_fsm

- Behavior supporting finite state machines (FSMs)
- Tail-call loop for maintaining state, like gen\_server
- States and events handled by app-specific callback module
- Allows events to be sent into an FSM either sync or async



# Riak And Gen\_\*

- Riak makes heavy use of these behaviors, e.g.:
  - FSMs for get and put operations
  - Vnode FSM
  - Gossip module is a gen\_server



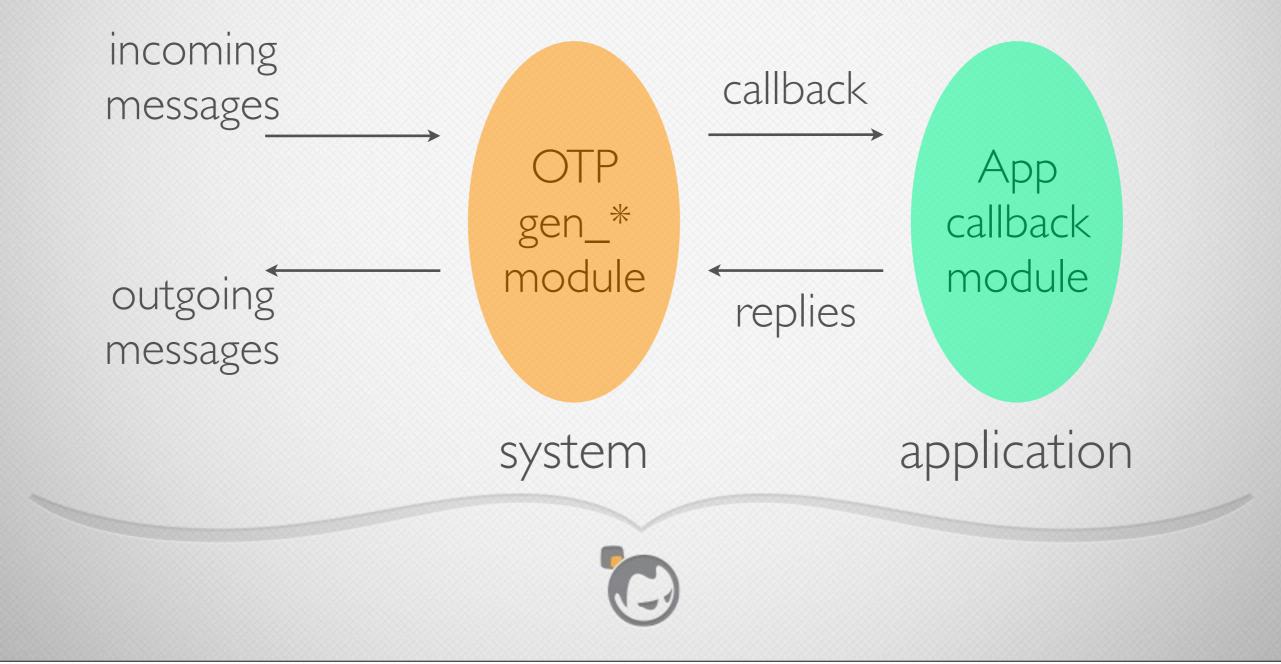
#### **Behavior Benefits**

- Standardized frameworks providing common patterns, common vocabulary
- Used by pretty much all non-trivial Erlang systems
- Erlang developers understand them, know how to read them



#### **Behavior Benefits**

• Separate a lot of messaging, debugging, tracing support, system concerns from business logic



#### Workers & Supervisors

- Workers implement application logic
- Supervisors:
  - start child workers and sub-supervisors
  - link to the children and trap child process exits
  - take action when a child dies, typically restarting one or more children

### Let It Crash

- In his doctoral thesis, Joe Armstrong, creator of Erlang, wrote:
  - Let some other process do the error recovery.
  - · If you can't do what you want to do, die.
  - Let it crash.
  - Do not program defensively.

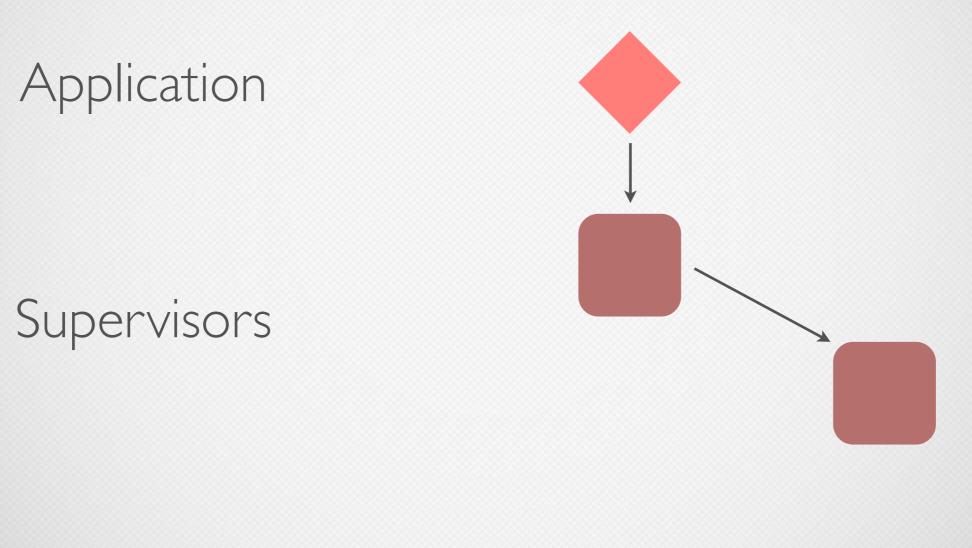
see <a href="http://www.erlang.org/download/armstrong\_thesis\_2003.pdf">http://www.erlang.org/download/armstrong\_thesis\_2003.pdf</a>



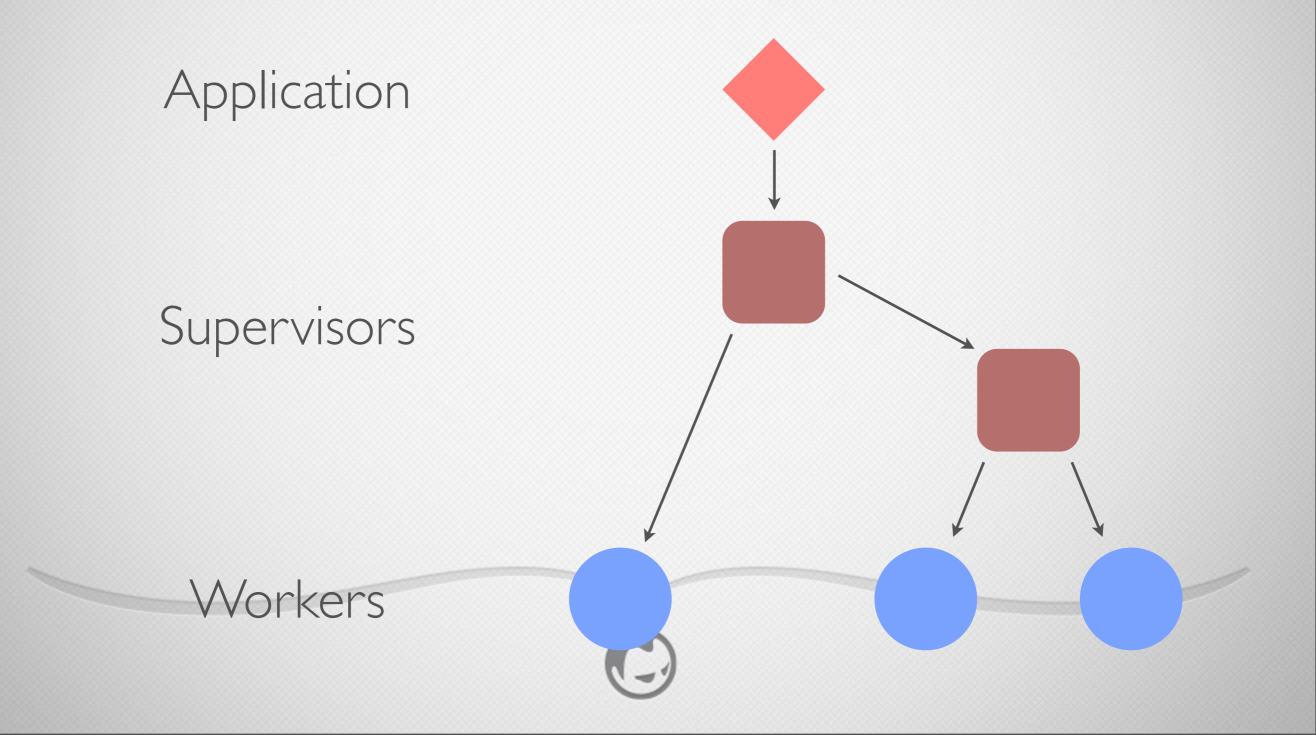


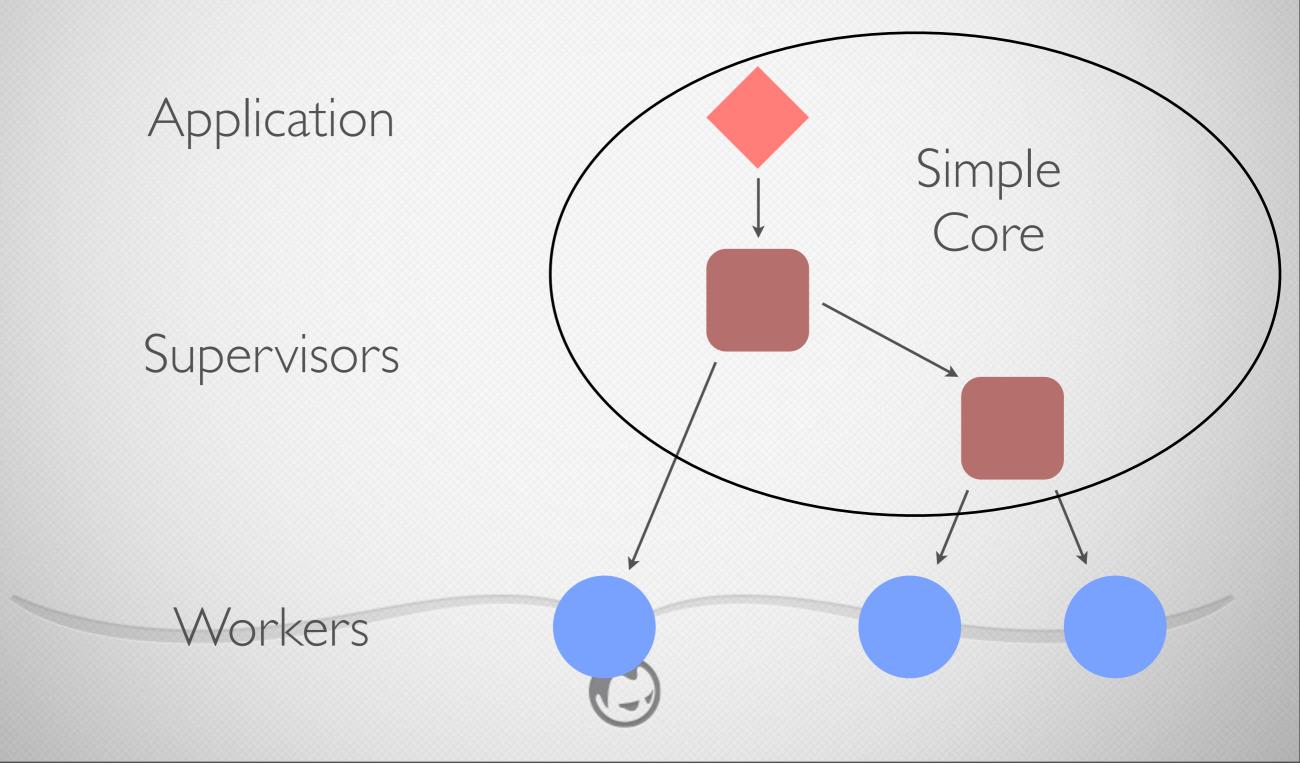
Application











# Erlang/OTP System Facilities

- Get status of an OTP process
- Get process info for any process
- Trace function calls, messages
- Releases
- Live upgrades

# INTEGRATION



#### **Riak Architecture**

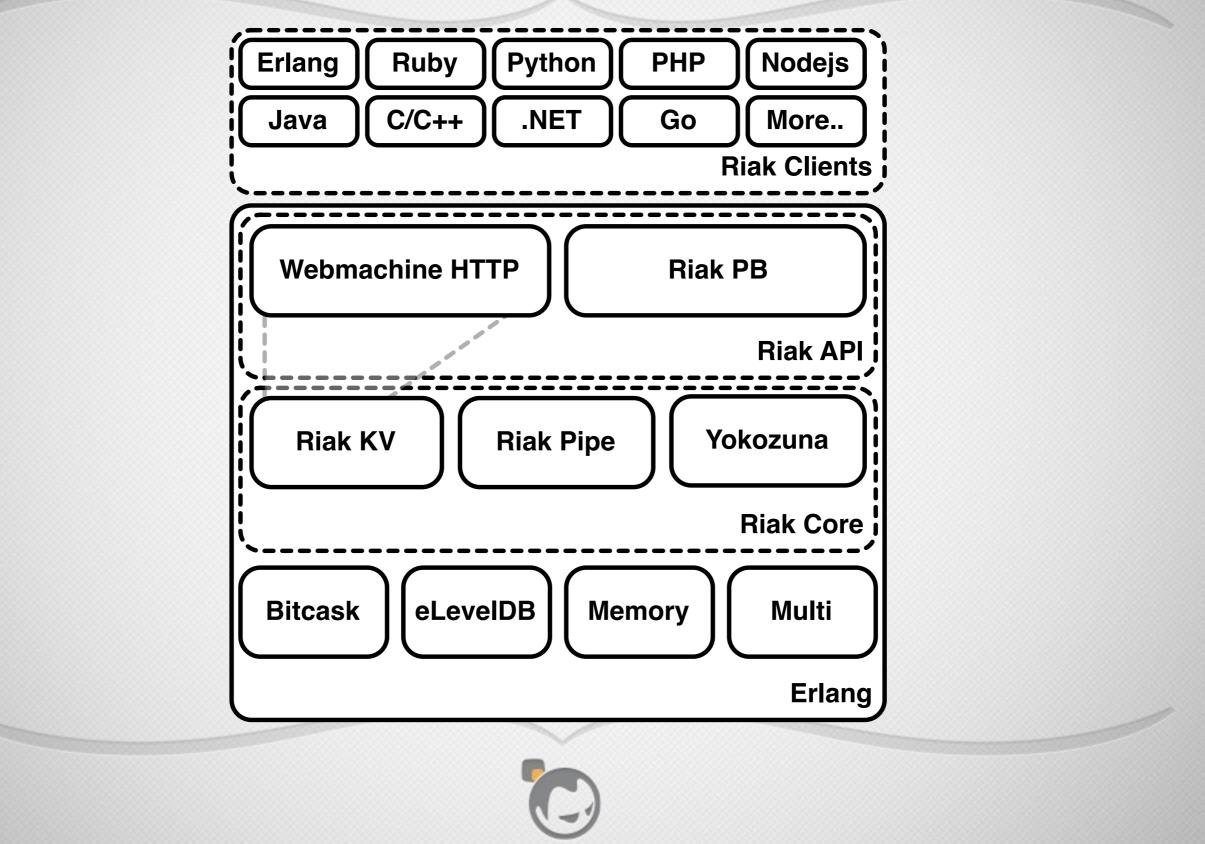


image courtesy of Eric Redmond, "A Little Riak Book" <u>https://github.com/coderoshi/little\_riak\_book/</u>

#### **Riak Architecture**

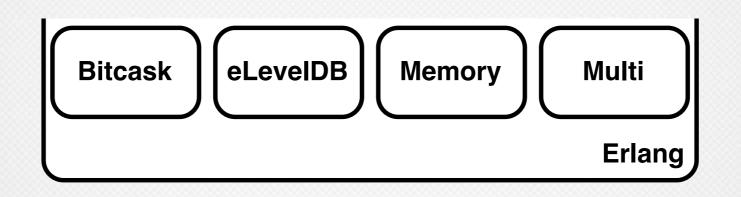


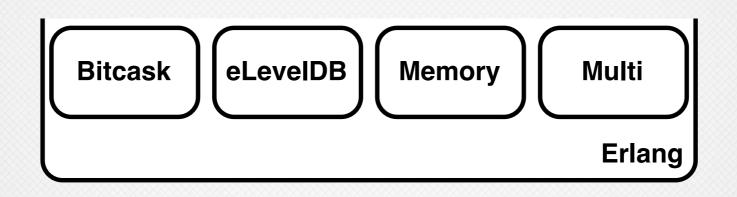


image courtesy of Eric Redmond, "A Little Riak Book" <u>https://github.com/coderoshi/little\_riak\_book/</u>

Wednesday, April 24, 13

#### **Riak Architecture**

#### Erlang on top



#### C/C++ on the bottom



# Linking With C/C++

- Erlang provides the ability to dynamically link C/C++ libraries into the VM
- One way is through the driver interface
  - for example the VM supplies network and file system facilities via drivers
- Another way is through Native Implemented Functions (NIFs)



#### Native Implemented Functions (NIFs)

- Lets C/C++ functions operate as Erlang functions
- Erlang module serves as entry point
- When module loads it dynamically loads its NIF shared library, overlaying its Erlang functions with C/C++ replacements



- NIF wrapper around Google's LevelDB C++ database
- Erlang interface plugs in underneath Riak KV



```
%% Erlang
open(Name, Opts) ->
erlang:nif_error({error, not_loaded}).
```



```
%% Erlang
open(Name, Opts) ->
erlang:nif_error({error, not_loaded}).
```

```
// C++
ERL_NIF_TERM
eleveldb_open(ErlNifEnv* env, int argc,
              const ERL_NIF_TERM argv[])
{
    char name [4096];
    if (enif_get_string(env,argv[0],name,
                         sizeof name, ERL_NIF_LATIN1) &&
        enif_is_list(env, argv[1]))
    ſ
```

# **NIF Features**

- Easy to convert arguments and return values between C/C++ and Erlang
- Ref count binaries to avoid data copying where needed
- Portable interface to OS multithreading capabilities (threads, mutexes, cond vars, etc.)



- Crashes in your linked-in C/C++ kill the whole VM
- Lesson: use NIFs and drivers only when needed, and don't write crappy code





### • NIF calls execute within a VM scheduler thread



- NIF calls execute within a VM scheduler thread
- If the NIF blocks, the scheduler thread blocks



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- If the NIF blocks, the scheduler thread blocks
- THIS IS VERY BAD



- NIF calls execute within a VM scheduler thread
- If the NIF blocks, the scheduler thread blocks
- THIS IS VERY BAD
- NIFs should block for no more than 1 millisecond



- Last fall Basho found "scheduler anomalies" where
  - the VM would put most of its schedulers to sleep, by design, under low load
  - but would fail to wake them up as load increased
- Caused by NIF calls that were taking multiple seconds in some cases
- Lesson: put long-running activities in their own threads



# Eunit

- Erlang's unit testing facility
- Support for asserting test results, grouping tests, setup and teardown, etc.
- Used heavily in Riak



# QuickCheck

- Property-based testing product from Quviq, invented by John Hughes (a co-inventor of Haskell)
- Create a model of the software under test
- QuickCheck runs randomly-generated tests against it
- When it finds a failure, QuickCheck automatically shrinks the testcase to a minimum for easier debugging
- Used heavily in Riak, especially to test various protocols and interactions

# MISCELLANEOUS



# Miscellaneous

- Memory
- Erlang shell
- Hot code loading
- VM knowledge
- Finding Erlang developers

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# Memory

- Process message queues have no limits, can cause outof-memory conditions if a process can't keep up
- By design, VM dies if it runs out of memory
- Apps like Riak run Erlang memory monitors that help log and notify about looming out-of-memory conditions

# Interactive Erlang Shell

- Hard to imagine working without it
- Huge help during development and debug



# Hot Code Loading

- It really works
- Use it all the time during development
- We've also used it to load repaired code into live production systems for customers (with their permission of course)



# VM Knowledge

- Running high-scale high-load systems like Riak requires knowledge of Erlang VM internals
- No different than working with the JVM or other language runtimes



# Finding Erlang Devs

- Erlang is easy to learn
- Not really a problem to hire Erlang programmers
- Basho hires great developers, those who need to learn Erlang just do it
- BTW we're hiring, see <u>http://bashojobs.theresumator.com</u>

# SUMMARY

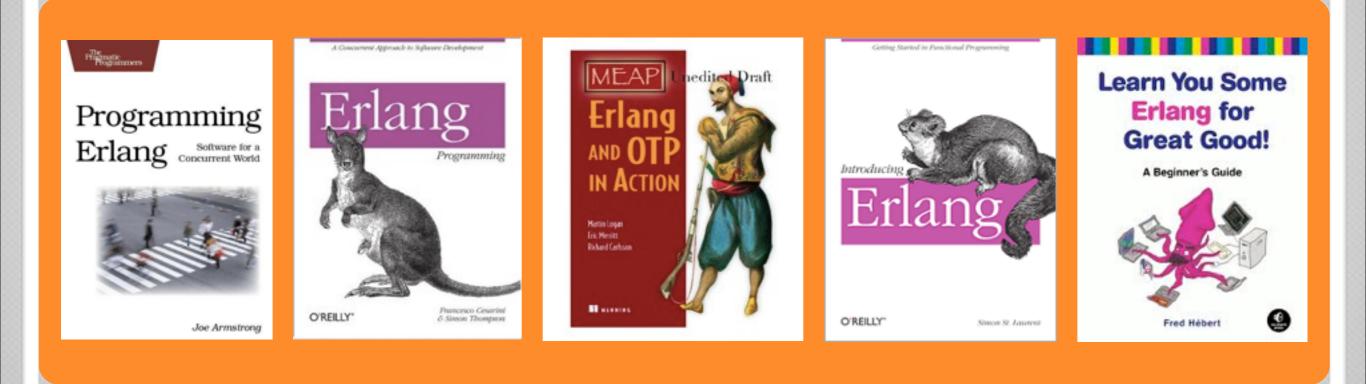


# Summary: Why Erlang For Riak?

- Distributed systems features
  - sort of a "distributed systems DSL"
- Concurrency features
- Reliability features
- Runtime introspection capabilities
- Individual developer and team productivity



# For More Erlang Info





# For More Riak Info

- "A Little Riak Book" by Basho's Eric Redmond https://github.com/coderoshi/little\_riak\_book/
- Mathias Meyer's "Riak Handbook" http://riakhandbook.com
- Eric Redmond's "Seven Databases in Seven Weeks" http://pragprog.com/book/rwdata/seven-databases-in-seven-weeks

# For More Riak Info

- Basho documentation <u>http://docs.basho.com</u>
- Basho blog <u>http://basho.com/blog/</u>
- Basho's github repositories <u>https://github.com/basho</u> <u>https://github.com/basho-labs</u>

# THANKS

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